

base manifold is of constant curvature  $-1$ , the non-zero eigenvalues of  $h$  are  $\pm 2$ , each with multiplicity  $n$ .

### 3. Integrals of scalar curvatures on symplectic and contact manifolds

We now want to consider a number of integral functionals defined on the set of metrics associated to a symplectic or contact structure. To begin we need to see how the set  $\mathcal{A}$  of associated metrics sits in the set  $\mathcal{M}$  of all Riemannian metrics with the same total volume; for a more detailed treatment see [5].

Let  $M$  be a symplectic manifold and  $g_t = g + tD + O(t^2)$  be a path of metrics in  $\mathcal{A}$ . We will use the same letter  $D$  to denote  $D$  as a tensor field of type  $(1,1)$  and of type  $(0,2)$ ,  $D^i_j = g^{ik}D_{kj}$ . Now

$$g(X, JY) = \Omega(X, Y) = g_t(X, J_t Y) = g(X, J_t Y) + tg(X, DJ_t) + O(t^2)$$

from which

$$J = J_t + tDJ_t + O(t^2).$$

Applying  $J_t$  on the right and  $J$  of the left we have

$$J_t = J + tJD + O(t^2).$$

Squaring this yields  $JDJ - D = 0$  and hence  $JD + DJ = 0$ . Conversely if  $D$  is a symmetric tensor field which anti-commutes with  $J$ , then  $g_t = ge^{tD}$  is a path of associated metrics. We summarize this and the corresponding result in the contact case as follows (cf.[5],[6]).

**Lemma 3.1.** *Let  $M$  be a symplectic or contact manifold and  $g \in \mathcal{A}$ . A symmetric tensor field  $D$  is tangent to a path in  $\mathcal{A}$  at  $g$  if and only if*

$$DJ + JD = 0 \tag{3.1}$$

*in the symplectic case and*

$$D\xi = 0, D\phi + \phi D = 0 \tag{3.2}$$

*in the contact case.*

Similar to the role played by Lemma 1.1 in critical point problems on  $\mathcal{M}$ , we have the following lemma for critical point problems on  $\mathcal{A}$ .

**Lemma 3.2.** *Let  $T$  be a second order symmetric tensor field on  $M$ . Then  $\int_M T^{ij}D_{ij} dV_g = 0$  for all symmetric tensor fields  $D$  satisfying (3.1) in the symplectic case and (3.2) in the contact case if and only if  $TJ = JT$  in the symplectic case and  $\phi T - T\phi = \eta \otimes \phi T\xi - (\eta \circ T\phi) \otimes \xi$  in the contact case (i.e.  $\phi$  and  $T$  commute when restricted to the contact subbundle).*

**Proof.** We give the proof in the symplectic case; the proof in the contact case being similar. Let  $X_1, \dots, X_{2n}$  be a local  $J$ -basis defined on a neighborhood  $\mathcal{U}$  (i.e.  $X_1, \dots, X_{2n}$  is

an orthonormal basis with respect to  $g$  and  $X_{2i} = JX_{2i-1}$ ) and note that the first vector field  $X_1$  may be any unit vector field on  $\mathcal{U}$ . Let  $f$  be a  $C^\infty$  function with compact support in  $\mathcal{U}$  and define a path of metrics  $g(t)$  as follows. Make no change in  $g$  outside  $\mathcal{U}$  and within  $\mathcal{U}$  change  $g$  only in the planes spanned by  $X_1$  and  $X_2$  by the matrix

$$\begin{pmatrix} 1 + tf + \frac{1}{2}t^2f^2 & \frac{1}{2}t^2f^2 \\ \frac{1}{2}t^2f^2 & 1 - tf + \frac{1}{2}t^2f^2 \end{pmatrix}.$$

It is easy to check that  $g(t) \in \mathcal{A}$  and clearly the only non-zero components of  $D$  are  $D_{11} = -D_{22} = f$ . Then  $\int_M T^{ij} D_{ij} dV_g = 0$  becomes

$$\int_M (T^{11} - T^{22})f dV_g = 0$$

Thus since  $X_1$  was any unit vector field on  $\mathcal{U}$ ,

$$T(X, X) = T(JX, JX)$$

for any vector field  $X$ . Since  $T$  is symmetric, linearization gives  $TJ = JT$ . Conversely, if  $T$  commutes with  $J$  and  $D$  anti-commutes with  $J$ , then  $\text{tr}TD = \text{tr}TJDJ = \text{tr}JTDJ = -\text{tr}TD$ , giving  $T^{ij} D_{ij} = 0$ .

**Theorem 3.3 (Blair-Ianus).** *Let  $M$  be a compact symplectic manifold and  $\mathcal{A}$  the set of metrics associated to the symplectic form. Then  $g \in \mathcal{A}$  is a critical point of  $A(g) = \int_M R dV_g$  if and only if the Ricci operator of  $g$  commutes with the almost complex structure corresponding to  $g$ .*

**Proof.** The proof is again to compute  $\frac{dA}{dt}$  at  $t = 0$  for a path  $g(t)$  in  $\mathcal{A}$ . Since all associated metrics have the same volume element this is easier than in the Riemannian case. In particular we have,

$$\begin{aligned} \left. \frac{dA}{dt} \right|_{t=0} &= \left. \frac{d}{dt} \int_M R_{kji}{}^k g^{ji} dV_g \right|_{t=0} \\ &= \int_M D_{kji}{}^k g^{ji} - R_{ji} D^{ji} dV_g \\ &= - \int_M R^{ji} D_{ji} dV_g, \end{aligned}$$

the other terms being divergences and hence contributing nothing to the integral. Setting  $\left. \frac{dA}{dt} \right|_{t=0} = 0$ , the result follows from Lemma 3.2.

We now review some known properties of almost Kähler manifold. First of all

$$\nabla_k J^k{}_l = 0, \tag{3.3}$$

$$(\nabla_k J_{ip}) J_j{}^p = (\nabla_p J_{ij}) J_k{}^p; \tag{3.4}$$

an almost Hermitian structure satisfying this last condition is called a *quasi-Kähler structure*.

The *\*-Ricci tensor* and the *\*-scalar curvature* are defined by

$$R_{ij}^* = R_{iklt} J^{kl} J_j^t, \quad R^* = R_i^{*i}.$$

The Ricci identity yields

$$\nabla_i \nabla_k J_j^t = (R_{kt} - R_{kt}^*) J_j^t$$

where  $R_{kt}^* J_j^t$  is skew-symmetric in  $j$  and  $k$ . Therefore

$$\nabla_t \nabla_k J_j^t + \nabla_t \nabla_j J_k^t = R_{kt} J_j^t + R_{jt} J_k^t. \quad (3.5)$$

The most important property of  $R^*$  is that

$$R - R^* = -\frac{1}{2} |\nabla J|^2$$

and hence  $R - R^* \leq 0$  with equality holding if and only if the metric is Kähler. Thus Kähler metrics are maxima of the functional

$$K(g) = \int_M R - R^* dV_g$$

on  $\mathcal{A}$  and the question that S. Ianus and I [8] were first interested in was whether these were the only critical points. The surprising result is that the critical point condition is again  $QJ = JQ$ ,  $Q$  denoting the Ricci operator.

**Theorem 3.4 (Blair-Ianus).** *Let  $M$  be a compact symplectic manifold and  $\mathcal{A}$  the set of metrics associated to the symplectic form. Then  $g \in \mathcal{A}$  is a critical point of  $K(g)$  if and only if  $QJ = JQ$ .*

**Proof.** To compute  $\frac{dK}{dt}$  at  $t = 0$ , we must differentiate  $R^* = R_{iklt} J^{kl} J^{it}$  along a path  $g(t)$  in  $\mathcal{A}$ . Since  $\Omega$  is fixed,

$$\left. \frac{\partial J_{ki}}{\partial t} \right|_{t=0} = 0, \quad \left. \frac{\partial J_j^i}{\partial t} \right|_{t=0} = -D^{im} J_{mj}, \quad \left. \frac{\partial J^{kl}}{\partial t} \right|_{t=0} = 0.$$

Then proceeding as before using (3.3)

$$\left. \frac{dK}{dt} \right|_{t=0} = \int_M [-R^{jm} + \nabla_i (J^{km} \nabla_k J^{ij}) + R^{*jm}] D_{jm} dV_g.$$

By Lemma 3.2, the critical point condition is that the symmetric part of the expression in brackets commutes with  $J$ . This is a long equation; some of its terms cancel by virtue of the quasi-Kähler condition (3.4) and the other terms combine by virtue of (3.5) to give the result.

The question as to whether or not on an almost Kähler manifold satisfying  $QJ = JQ$  is Kählerian seems to be difficult. In [13] S. I. Goldberg showed that if  $J$  commutes

with the curvature operator, then the metric is Kählerian and conjectured that a compact almost-Kähler Einstein manifold is Kählerian. K. Sekigawa [20] proved that a compact almost-Kähler Einstein manifold with non-negative scalar curvature is Kählerian.

In [9] A. J. Ledger and I proved the contact analogues of these theorems, which we present here without proof.

**Theorem 3.5 (Blair-Ledger).** *Let  $M$  be a compact contact manifold and  $\mathcal{A}$  the set of metrics associated to the contact form. Then  $g \in \mathcal{A}$  is a critical point of  $A(g) = \int_M R dV_g$  if and only if  $Q$  and  $\phi$  commute when restricted to the contact subbundle.*

This integral was further studied in dimension 3 by D. Perrone [19], who gave the critical point condition as

$$\nabla_\xi h = 0.$$

To see this, recall that in dimension 3, the Ricci operator determines the full curvature tensor, i.e.

$$\begin{aligned} R(X, Y)Z &= (g(Y, Z)QX - g(X, Z)QY + g(QY, Z)X - g(QX, Z)Y) \\ &\quad - \frac{R}{2}(g(Y, Z)X - g(X, Z)Y). \end{aligned}$$

Therefore the operator  $l$  defined  $lX = R(X, \xi)\xi$  by is given by

$$lX = QX - \eta(X)Q\xi + g(Q\xi, \xi)X - g(QX, \xi)\xi - \frac{R}{2}(X - \eta(X)\xi)$$

from which

$$(l\phi - \phi l)X = (Q\phi - \phi Q)X + \eta(X)\phi Q\xi - g(Q\phi X, \xi)\xi. \quad (3.6)$$

Thus the critical point condition is  $l\phi - \phi l = 0$ . Now recall equations (2.2) and (2.3), viz.  $\frac{1}{2}(-l + \phi l\phi) = h^2 + \phi^2$  and  $\nabla_\xi h = \phi - \phi h^2 - \phi l$ . Applying  $\phi$  to the first of these and adding to the second gives  $\nabla_\xi h = \frac{1}{2}(l\phi - l\phi)$  and thus the critical point condition may be expressed as  $\nabla_\xi h = 0$ .

In the contact case the  $*$ -scalar curvature is defined by  $R^* = R_{iklt}\phi^{kl}\phi^{it}$  and it was shown by Olszak [18] that

$$R - R^* - 4n^2 = -\frac{1}{2}|\nabla\phi|^2 + 2n - \text{tr}h^2 \leq 0$$

with equality holding if and only if the metric is Sasakian.

**Theorem 3.6 (Blair-Ledger).** *Let  $M$  be a compact contact manifold and  $\mathcal{A}$  the set of metrics associated to the contact form. Then  $g \in \mathcal{A}$  is a critical point of  $K(g) = \int_M R - R^* - 4n^2 dV_g$  if and only if  $Q - 2nh$  and  $\phi$  commute when restricted to the contact subbundle.*

In dimension 3, the argument giving Perrone's result gives the critical point condition as  $\nabla_\xi h = -2\phi h$ , a condition that will be important in the next lecture.

For contact manifolds of general odd dimension, if  $g$  is critical for both  $A$  and  $K$ ,  $h = 0$  so  $\xi$  is Killing. To see this note that the commutativities of Theorems 3.5 and 3.6 together imply that  $\phi h = h\phi$  but  $\phi h = -h\phi$  and hence  $h = 0$  easily follows. As with the almost Kähler case, the question of whether or not a K-contact structure satisfying  $Q\phi = \phi Q$  is Sasakian would seem to be difficult.

#### 4. Integral of the Ricci curvature in the direction of the characteristic vector field

We devote this section to a discussion of a particular functional defined on the set of metrics associated to a contact structure. The main theorem is the following [6].

**Theorem 4.1 (Blair).** *Let  $M$  be a compact regular contact manifold and  $\mathcal{A}$  the set of metrics associated to the contact form. Then  $g \in \mathcal{A}$  is a critical point of  $L(g) = \int_M Ric(\xi) dV_g$  if and only if  $g$  is K-contact.*

One might conjecture this without the regularity, however we have the following counterexample: The standard contact metric structure on the tangent sphere bundle of a compact surface of constant curvature  $-1$  is a critical point of  $L$  but is not K-contact. It is a result of Y. Tashiro [23] that the standard contact metric structure on the tangent sphere bundle of a Riemannian manifold is K-contact if and only if the base manifold is of constant curvature  $+1$ . Also recall the result of [4] that the standard contact structure of the tangent sphere bundle of a compact Riemannian manifold of non-positive constant curvature is not regular. Our second result is the following theorem [7].

**Theorem 4.2 (Blair).** *Let  $T_1M$  be the tangent sphere bundle of a compact Riemannian manifold  $(M, G)$  and  $\mathcal{A}$  the set of all Riemannian metrics associated to its standard contact structure. Then the standard associated metric is a critical point of the functional  $L(g)$  if and only if  $(M, G)$  is of constant curvature  $+1$  or  $-1$ .*

Recall that by a K-contact structure we mean a contact metric structure for which  $\xi$  is Killing and that this is the case if and only if  $h = 0$ . Recall also equation (2.4), viz.

$$Ric(\xi) = 2n - tr h^2.$$

Thus K-contact metrics when they occur are maxima for the function  $L(g)$  on  $\mathcal{A}$ . Also the critical point question for  $L(g)$  is the same as that for  $\int_M |h|^2 dV_g$  or  $\int_M |\tau|^2 dV_g$  where  $\tau(X, Y) = (\mathcal{L}_\xi g)(X, Y) = 2g(X, h\phi Y)$ . This last integral was studied by Chern and Hamilton [11] for 3-dimensional contact manifolds as a functional on  $\mathcal{A}$  regarded as the set of CR-structures on  $M$  (there was an error in their calculation of the critical point condition as was pointed out by Tanno[22]).

**Proof of Theorem 4.1.** As with our other critical point problems, the first step is to compute  $\frac{dL}{dt}$  at  $t = 0$  for a path  $g(t) \in \mathcal{A}$

$$\left. \frac{dL}{dt} \right|_{t=0} = \int_M (-h^i_m h^{mk} - R^k_{rs}{}^i \xi^r \xi^s + 2h^{ik}) D_{ik} dV_g.$$